## MTAT.07.003 CRYPTOLOGY II

# Security of Protocols

Sven LaurUniversity of Tartu

### Primitives and protocols

Cryptographic primitives. Primitives are tailor-made constructions that have to preserve their security properties in very specific scenarios.

- ⊳ IND-CPA cryptosystem is guaranteed to be secure *only* with respect to the simplistic games that define IND-CPA security.
- ⊳ A binding commitment is secure *only* against double opening.

Cryptographic protocols. Protocols must preserve security under the widerange of conditions that are implicitly specified by security model.

- $\triangleright$  An adversary might try to learn inputs of honest parties.
- $\triangleright$  An adversary might try to change the outputs of honest parties.
- $\triangleright$  An adversary might force honest parties to compute something else.
- $\triangleright$  An adversary might try to learn his or her outputs so that honest parties learn nothing about their outputs.

### Security against <sup>a</sup> specific security goa<sup>l</sup>

For each specific security goal and input distribution  $\mathfrak D$ , we can construct a security game  $\mathcal{G}_\mathrm{real}$  that models the corresponding protocol run.



Any well-defined security goal can be formalised as a predicate  $\mathcal{B}(\cdot).$  It is common to model the adversary  ${\mathcal A}$  as a dedicated entity in the model.

### Relevant attack scenarios

No protocol can be secure against all imaginable attacks and security goals. Hence, we have to specify the answer for the following questions.

- $\diamond$  What is tolerated adversarial behaviour?
- $\diamond$  What type of predicates  $\mathcal{B}(\cdot)$  are considered relevant?
- $\diamond$  What is the model of communication and computations?
- $\diamond$  In which context the protocol is executed?
- $\diamond$  When is a plausible attack successful enough?

**Common security levels.** Let  $\mathfrak B$  be the set of relevant predicates.

- ⊲ If B consists of all predicates then we talk about statistical security.
- $\triangleright$  If  $\mathfrak B$  is a set of all  $t$ -time predicates, we talk about *computational security*.

# Resilience Principle

## Resilience principle

Let  $\pi_{\alpha}$  and  $\pi_{\beta}$  be protocols such that any plausible attack  ${\cal A}$  against  $\pi_{\alpha}$  can be converted to a plausible attack against the  $\pi_\beta$  roughly with the same success rate. Then protocol  $\pi_\alpha$  is as secure as  $\pi_\beta$ . We denote it  $\pi_\beta \preceq \pi_\alpha$ .

**Ideal implementation.** For any functionality  ${\mathcal F}$ , we can consider the ideal implementation  $\pi^\circ$ , which uses *unconditionally trusted third party*  $\mathfrak{T}$ :

- 1. All parties submit their inputs to a trusted party  $\mathfrak T$ .
- $2.$   $\mathcal T$  computes and sends the desired outputs back.

**Resilience principle.** An ideal implementation  $\pi^{\circ}$  is as secure as any protocol  $\pi$  that correctly implements the functionality  ${\mathcal F}$ . Any protocol  $\pi \succeq \pi^\circ$  achieves maximal security level for any relevant security goal  $\mathcal{B}(\cdot).$ 

### Ideal vs real world paradigm

Let  $\mathcal{G}_\mathrm{id-atk}$  and  $\mathcal{G}_\mathrm{re-atk}$  be the games that model the execution of an ideal and real protocols  $\pi^\circ$  and  $\pi$  and let  $\mathcal{A}^\circ$  and  $\mathcal{A}$  be the corresponding real and ideal world adversaries. Then we can compare the following games.

$$
\begin{array}{ll}\n\mathcal{G}^{\mathcal{A}^{\circ}}_{\text{ideal}} & \mathcal{G}^{\mathcal{A}}_{\text{real}} \\
\hspace{2cm} \left[ \begin{array}{c} \phi \leftarrow \mathfrak{D} \\ \psi^{\circ} \leftarrow \mathcal{G}^{\mathcal{A}^{\circ}}_{\text{id-atk}}(\phi) \end{array} \right. & \left[ \begin{array}{c} \phi \leftarrow \mathfrak{D} \\ \psi \leftarrow \mathcal{G}^{\mathcal{A}}_{\text{re-atk}}(\phi) \\ \text{return } \mathfrak{B}(\psi^{\circ}) \end{array} \right. & \left[ \begin{array}{c} \phi \leftarrow \mathfrak{D} \\ \psi \leftarrow \mathcal{G}^{\mathcal{A}}_{\text{re-atk}}(\phi) \\ \text{return } \mathfrak{B}(\psi) \end{array} \right. \right.\n\end{array}
$$

Now  $\pi^\circ$ there exists a  $t_{\operatorname{id}}$ -time ideal world adversary  $\mathcal{A}^{\circ}$  such that  $\frac{1}{2} \circ \preceq \pi$  if for any  $\mathcal{B} \in \mathfrak{B}$  and for any  $t_{\text{re}}$ -time real world adversary<br>vists a to time ideal world adversary 1° such that

$$
|\mathrm{Pr}\left[\mathcal{G}^\mathcal{A}_{\mathrm{real}}=1\right]-\mathrm{Pr}\left[\mathcal{G}^{\mathcal{A}^\circ}_{\mathrm{ideal}}=1\right]| \leq \varepsilon \enspace .
$$

### Simulation principle



The correspondence  $\mathcal{A},\mathcal{B}\mapsto \mathcal{A}^{\circ}$  is usually implemented by  $\boldsymbol{s}$ imulator  $\mathcal{S}$  that act as a translator between real world adversary.  $\mathcal{A}$  and ideal world act as a translator between real world adversary A and ideal world.<br>MTAT.07.003.Cryptology.IL Security of Protocols 6 May 2009.

MTAT.07.003 Cryptology II, Security of Protocols, <sup>6</sup> May, <sup>2009</sup> $\overline{9}$  6

# Standalone Security Model

Two Parties and Static Corruption

### Formal description

 ${\sf Computational\ context.}$  The protocol  $\pi$  is executed once with the inputs  $x_1, x_2$  and auxiliary information  $\sigma_1, \sigma_2$ , i.e.,  $\phi_1 = (x_1, \sigma_1)$  and  $\phi_2 = (x_2, \sigma_2)$ .  $x_1,x_2$  and auxiliary information  $\sigma_1,\sigma_2$ , i.e.,  $\phi_1=(x_1,\sigma_1)$  and  $\phi_2=(x_2,\sigma_2)$ .<br>The output of honest parties is  $\psi_i=(y_i,\sigma_i)$  where  $y_i$  is the protocol output.

**Corruption model.** Adversary can corrupt one party before the protocol. A *semihonest* adversary only observes the computations done by the corrupted party. A *malicious* adversary can alter the behaviour of the party.

Communication model. Each party sends and receives one message during <sup>a</sup> round. <sup>A</sup> maliciously corrupted party can send his or her message thehonest party has sent his or her message (*rushing adversary*).

**Ideal world model.** Both parties submit their inputs  $x_1, x_2$  to  $\mathcal T$  who computes the corresponding outputs  $y_1, y_2$ . Party  $\mathcal{P}_1$  gets his or her input  $y_1$  first and *maliciously* corrupted  $\mathcal{P}_1$  *can abort* the protocol after that.

### Classical security definitions

#### Statistical security

A protocol is  $(t_{\rm re}, t_{\rm id}, \varepsilon)$ -secure if for any  $t_{\rm re}$ -time real world adversary  ${\cal A}$ there exists a  $t_{\operatorname{id}}$ -time ideal world adversary  $\mathcal{A}^{\circ}$  such that for any input distribution  $\frak D$  the output distributions  $\psi$  and  $\psi^\circ$  are statistically  $\varepsilon$ -close.

#### Computational security

A protocol is  $(t_{\rm re}, t_{\rm id}, t_{\rm pred}, \varepsilon)$ -secure if for any  $t_{\rm re}$ -time real world adversary A there exists a  $t_{\rm id}$ -time ideal world adversary  $\mathcal{A}^{\circ}$  such that for any input<br>distribution  $\Omega$  the certaat distributions described? sus  $(t-\epsilon)$  also distribution  $\mathfrak D$  the output distributions  $\psi$  and  $\psi^\circ$  $^{\circ}\,$  are  $(t_{\mathrm{pred}}, \varepsilon)$ -close.

# Examples

### Protocol for rock-paper-scissors game



Assume that  $(\mathsf{Gen}, \mathsf{Com}, \mathsf{Open})$  is perfectly binding commitment scheme. Let  $x_1\circledast x_2$  denote the outc  $y = (x_1, x_2, x_1 \circledast x_2)$  denote the desired end result of the game.  $_2$  denote the outcome of the game for  $x_1, x_2$  $\mathbf{z}_2 \in \{0,1,2\}$  and

MTAT.07.003 Cryptology II, Security of Protocols, <sup>6</sup> May, <sup>2009</sup>

### Simulator for the first player

```
\mathcal{S}^{\mathcal{P}}∗^1(\sigma_1,x_1)\bigcap \big(\mathsf{pk}, c\big)\begin{array}{c} \end{array}\longleftarrow\mathcal P∗
1\left(σ_{1},x1\left( \begin{array}{c} 1 \end{array} \right)Use rewinding to get
       \overline{\phantom{a}}\mid d0\longleftarrow\mathcal P∗_{1}^{*}(0),d1\longleftarrow\mathcal P∗j_{1}^{*}(1),d2\longleftarrow\mathcal P∗_{1}^{*}(2)Compute
                             \mathcal{X}% =\mathbb{R}^{2}\times\mathbb{R}^{2}\begin{matrix} i \ 1 \end{matrix}\leftarrow Open<sub>pk</sub>(c, d_i) for i \in \{0, 1, 2\}.
     Send 0 to \mathfrak T if none of the decommitments are valid.
     Otherwise send xGiven y form \mathfrak T store d \leftarrow {\mathfrak P}_1^*i \neq \perp to \mathfrak{T}.
                                                               Contract Contract State
                                                                           ^{*}_{1}(%x_2).
     If \mathsf{Open}_{\mathsf{pk}}(c,d) =\perp then order \mathfrak T to halt the computations.
     \mathsf{Output} whatever \mathcal{P}^*_1\hat{1} outputs.
```
### Simulator for the second player

We cannot build simulator for the second player since  $\hat{x}_2$  sent to  $\mathcal{P}_1$  may depend on the commitment value and the following code fragment fails

$$
\mathcal{S}^{\mathcal{P}^*_2}(\sigma_2, x_2)
$$
\n
$$
\begin{bmatrix}\n\mathsf{pk} \leftarrow \mathsf{Gen} \\
(c, d) \leftarrow \mathsf{Com}_{\mathsf{pk}}(0) \\
\mathsf{Send} \ \hat{x}_2 \leftarrow \mathcal{P}^*_2(\sigma_2, x_2, c) \text{ to } \mathcal{T}.\n\end{bmatrix}
$$
\nGiven  $y$  from  $\mathcal{T}$  rewind until success.\n
$$
\begin{bmatrix}\n(c, d) \leftarrow \mathsf{Com}_{\mathsf{pk}}(x_1) \\
\text{If } \mathcal{P}^*_2(\sigma_2, x_2, c) \neq \hat{x}_2 \text{ repeat the cycle.} \\
\text{Output whatever } \mathcal{P}^*_2 \text{ does.}\n\end{bmatrix}
$$

### Further analysis

If commitment scheme is  $(t_{\mathrm{re}},\varepsilon)$ -hiding then probabilities

$$
\alpha(x_1, x_2) = \Pr[\mathsf{pk} \leftarrow \mathsf{Gen}, (c, d) \leftarrow \mathsf{Com}_{\mathsf{pk}}(x_1) : \mathcal{P}_2^*(c) = x_2]
$$

can vary at most  $\varepsilon$  if we alter  $x_1$ . Hence, on average after  $\frac{1}{\alpha(0,x_2)-\varepsilon}$  the rewinding succeeds and the continuation of the simulation is perfect.

As the running-time must be finite, <sup>a</sup> nonzero failure probability causesstatistical difference. The statistical difference comes from two sources:

- $\triangleright$  The distribution of inputs  $\hat{x}_2$  submitted to  $\mathfrak T$  is different from the distribution of  $\hat{x}_2$  over the real protocol runs.
- $\triangleright$  A nonzero simulation failure cause secondary difference.

### Coin flipping by telephone



The protocol above assures that participants output <sup>a</sup> uniformly distributedbit even if one of the participants is malicious.

- $\triangleright$  If the commitment scheme is perfectly binding, then Lucy can also generate public parameters for the commitment scheme.
- $\triangleright$  If the commitment scheme is perfectly hiding, then Charlie can also generate public parameters for the commitment scheme.

### Simulator for the second party

 $\mathcal S$ P∗ $^{2}(\phi$  $_2, y)$  $\sqrt{2}$  $\overline{\phantom{a}}$ pk  $\leftarrow$  Gen For $i = 1, \ldots k$  do  $\begin{bmatrix} \phantom{-} \end{bmatrix}$  $\begin{array}{c} \end{array}$  $\it b$  $v_1$  $\overleftarrow{u}$  $\sqrt{u}\left\{0,1\right\}$  $(c,d)$  $\leftarrow \mathsf{Com}_{\mathsf{pk}}($  $\it b$  $v_1$  $\left( \begin{array}{c} 1 \end{array} \right)$  $\it b$  $v_2$  $\longleftarrow$  $\mathcal P$ ∗ 2 $(\phi$  $_{2},$  pk,  $c)$ if  $b$  $v_1$ ⊕ $\it b$  $v_2$ = $y$  then  $\overline{\phantom{a}}$  Send $d$  to  $\mathcal P$ ∗ 2 $_2^*$  and output whatever  ${\mathcal P}$ ∗ $\frac{1}{2}$  outputs. returnreturn Failure

## Failure probability



If commitment scheme is  $(k\cdot t, \varepsilon_1)$ -hiding, then for any  $t$ -time adversary  $\mathcal{P}^*_2$ the failure probability

$$
\Pr\left[\mathsf{Failure}\right] \leq \Pr\left[\mathcal{S}_{2}^{\mathcal{P}_{2}^{*}}(y) = \mathsf{Failure}\right] + k \cdot \varepsilon_{1} \leq 2^{-k} + k \cdot \varepsilon_{1}.
$$

### The corresponding security guarantee

If the output  $y$  is chosen uniformly over  $\{0,1\}$ , then the last effective value of  $b_1$  has also an almost uniform distribution:  $\left|\Pr\left[b_1=1 | \neg \mathsf{Failure}\right] -\frac{1}{2}\right| \leq 1$  $k\cdot\varepsilon_1$ . Hence, for  $\mathcal{P}^\circ_2$  $_{1} = 1| \neg$ Failure $]-{1 \over 2}$  2 $\vert \leq$  $_2^{\circ}=\mathcal{S}^{\mathcal{P}}$ ∗ $^{\rm 2}$  the outputs of games

$$
\mathcal{G}_{\text{ideal}}^{\mathcal{P}_2^{\circ}}
$$
\n
$$
\left[\n\begin{array}{cc}\n(\phi_1, \phi_2) \leftarrow \mathfrak{D} & \mathcal{G}_{\text{real}}^{\mathcal{P}_2^*} \\
y \leftarrow \{0, 1\} & \mathfrak{P}_1 \text{ and } \mathfrak{P}_2^* \text{ run the protocol.} \\
\psi_1 \leftarrow (\phi_1, y) & \psi_1 \leftarrow \mathfrak{P}_1 \\
\psi_2 \leftarrow \mathcal{S}_2^{\mathcal{P}_2^* (\phi_2)} & \psi_2 \leftarrow \mathfrak{P}_2^* \\
\text{return } (\psi_1, \psi_2) & \text{return } (\psi_1, \psi_2)\n\end{array}\n\right]
$$

are at most  $k \cdot \varepsilon_2$ statistical distance between output distributions is at most  $2^{-k} + 2k \cdot \varepsilon_1.$  $_2$  apart if the run of  $\mathcal{S}_2^\mathcal{P}$ ∗ $\frac{^J}{2}$  $\frac{1}{2}$  is successful. Consequently, the

### Simulator for the first party

 $\mathcal{S}^{\mathcal{P}}$  $\stackrel{*}{\scriptscriptstyle\perp}(\phi_1,y)$  $\begin{bmatrix} \phantom{-} \end{bmatrix}$ l l l  $\lfloor$ pk  $\leftarrow$  Gen  $,c \leftarrow \mathcal{P}_1^*(\phi_1, \mathsf{pk})$ Rewindd  $\mathcal{P}_1$  to get  $d$  $\mu_0$  $\longleftarrow$  $\mathcal P$  $i(0), d_1 \leftarrow$  $\mathcal P$  $_{1}^{*}(1)$ b  $\mathbf{0}_1^0 \leftarrow \mathsf{Open}_{\mathsf{pk}}(c,d_0),\,\, \mathbb{b}_1^1$  $\frac{1}{1} \leftarrow \mathsf{Open}_{\mathsf{pk}}(c, d_1)$ if  $\bot \neq b_1^0 \neq b_1^1 \neq \bot$  then Failure if  $b_1^0 = \bot = b_1^1$  then  $\int$  Send the Halt command to  $\mathfrak{T}$ . | Choose  $b_2 \leftarrow \{0, 1\}$  and re-run the protocol with  $b_2$ .  $\left\lfloor \right.$  Return whatever  $\mathcal{P}_{1}^{*}$  returns. if  $b_1^0 = \perp$  then  $b_1 \leftarrow$  $b_1^0 = \perp$  then  $b_1 \leftarrow b$  $b_2 \leftarrow b_1 \oplus y$  $\frac{1}{1}$  else  $b_1 \leftarrow b$ 0 1Re-run the protocol with  $\overline{b}_2$ if  $b_1^{b_2} = \bot$  then Send the Halt command to T. Return whatever  $\mathcal{P}^*_1$  returns.

### Further analysis

If the commitment scheme is  $(t,\varepsilon_2)$ -binding, then the failure probability is less than  $\varepsilon_2.$  If the output  $y$  is chosen uniformly over  $\{0,1\}$ , then the value of  $b_2$  seen by  $\mathcal{P}^{\ast}_1$  is uniformly distributed.

Consequently, the output distributions of  $\mathcal{S}^{\mathcal{P}^*_1}$  and  $\mathcal{P}_2$  in the ideal world coincide with the real world outputs if  ${\cal S}$  does not fail.

### Resulting security guarantee

**Theorem.** If a commitment scheme is  $(k \cdot t, \varepsilon_1)$ -hiding and  $(t, \varepsilon_2)$ -binding, then for any plausible  $t$ -time real world adversary there exists  $\mathrm{O}(k\cdot t)$ -time ideal world adversary such that the output distributions in the real and ideal world are  $\max\left\{2^{-k}+2k\cdot\varepsilon_1,\varepsilon_2\right\}$ -close.